

CONTROL SYSTEM

UNIT I SYSTEMS AND REPRESENTATION 9

Basic elements in control systems: – Open and closed loop systems – Electrical analogy of mechanical and thermal systems – Transfer function – AC and DC servomotors – Block diagram reduction techniques – Signal flow graphs.

UNIT II TIME RESPONSE 9

Time response: – Time domain specifications – Types of test input – I and II order system response – Error coefficients – Generalized error series – Steady state error – Root locus construction- Effects of P, PI, PID modes of feedback control –Time response analysis.

UNIT III FREQUENCY RESPONSE

9

Frequency response: – Bode plot – Polar plot – Determination of closed loop response from open loop response - Correlation between frequency domain and time domain specifications

UNIT IV STABILITY AND COMPENSATOR DESIGN 9

Characteristics equation – Routh Hurwitz criterion – Nyquist stability criterion- Performance criteria – Effect of Lag, lead and lag-lead compensation on frequency response-Design of Lag, lead and laglead compensator using bode plots.

UNIT V STATE VARIABLE ANALYSIS 9

Concept of state variables – State models for linear and time invariant Systems – Solution of state and output equation in controllable canonical form – Concepts of controllability and observability.